

#### APPLICATIONS

Proximity switches can be used in many control functions and in particular they can operate even in the most arduous conditions exceeding the performance of any type of mechanical switch. The most frequent applications are:

- · Limit switch without contact
- Detection of working pieces
- Sequence detection
- Detection of rotating or linear speed
- Incremental encoder function (2 sensors with 90° out of phase signals)
- Measurements of thickness and smoothness of metallic sheets (linear sensors)
- Detection of materials and alloys composition (linear sensors)

#### BENEFITS

The use of proximity sensors solves all the difficult problems of automation and detection in industrial and automotive places.

Compared to traditional mechanical micro-switches, they offer more advantages:

- No physical contact is required for operation
- Elimination of contact oxidation, due to solid state switching components
- No sparking of contacts; types ATEX (Ex) can operate in environments with explosive gas or inflammable liquids and solvents vapours
- Impermeableness against liquids, oils, powders, thanks to the resin clad
- High resistance against vibrations and impacts
- · Very long life time thanks to non-electromechanical circuits
- No bounces on the switching edges
- Possibility of direct connecting to logical circuits and counters
- Almost unlimited life time non depending by the number of cycles

#### STANDARDS

# Conformities (E

In accordance with the European Directives 2004/108/EC and 2006/95/EC, all products are in accordance with the rules for electromagnetic compatibility and safety standards for low voltage machinery.

These standards are met in accordance with EN60947-5-2.

#### **Namur Sensors non-amplified**

The non-amplified d.c. sensors are built according to EN60947-5-6 standards.

#### Amplified sensors

The amplified d.c. types (DCA and AC types) are manufactured according to EN60947-5-2.

#### **ATEX** sensors

For potentially explosive atmosphere applications a wide range of sensors is available certified according to the ATEX directive 94/9/EC. Please refere to the specific catalogue.

#### CABLE CHARACTERISTICS

All the standard sensor cables are manufactured from flexible PVC type with flammability resistance according to CEI 20-22 II - IEC 332.3A, with these characteristics:

- conductor formation according to VDE 0295 class 6
- insulation: PVC flammability resistance
- sheath: YM2 flammability resistance to VDE 0209/3.69

The standard cable length is 2 metres, however it is possible on request to have different cable lengths. It is also possible to have BDC sensors with PUR (polyurethane) sheath, particularly impervious against oils, acids or continuous stress. The cables can also be supplied with insulation and thermoplastic elastomer sheath (TPE-O) for temperatures from - 40° up to +140° C (sensors for high-low temperatures).



#### Shock by EN 60068-2-27

Max acceleration: 50 gImpulse time: 11 ms

#### Vibrations to EN 60068-2-6

Frequency range: 10 ÷ 55 Hz

Amplitude: ± 2 mm.

#### DEGREE OF PROTECTION

According to EN60529

IP 6X: against ingress of dust-tight. IP 65: water jets from all directions.

IP 67: immersion for 30 min. under 1 m. depth of water.

IP 68: extended immersion in water at conditions agreed between user and manufacturer. Please contact our technical office for further details.

According to DIN40050

IP 69K: high pressure/steam water jet cleaning.

# DESCRIPTION OF THE TECHNICAL TERMS IN THE CATALOGUE

#### RATED OPERATING DISTANCE (S<sub>n</sub>)

The rated operating distance is a nominal value used to designate the operating distance. Manufacturing tolerances and external factors are not taken into account. Fig. 1 shows the relation between the operating distance  $(S_n, S_r, S_a)$  and the hysteresis (H).

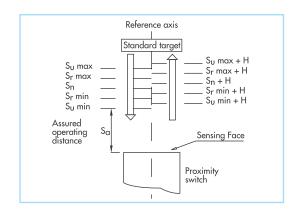


Fig. 1

#### STANDARD TARGET

The target used for the sensing distance is referenced to FE360 square steel sheet 1mm thick and with side the diameter of the circle on the active surface of the sensing face, or three times the rated operating distance Sn if this is more than the diameter. If the object to sense is of a different material, the rated operating distance is determined by multiplying the effective operating distance (Sr) by one of the following reduction factors:

#### **Inductive Sensors**

- stainless steel	$0.3 \div 0.4$
- brass	$0.35 \div 0.50$
- aluminum	$0.35 \div 0.50$
- copper	$0.25 \div 0.45$

#### **Capacitive Sensors**

- metal	1
- water	1
- PVC	0,5
- wood	0,25
- clothes	0,15
- paper	0,1

These reductions are not valid for the slot types, on which the switching point is almost indipendent of the metal used.



#### REAL OPERATING DISTANCE (Sr)

The real operating distance is measured with rated voltage and with a temperature of  $23 \pm 5^{\circ}$ C. It must be between the 90% and 110% of the rated operating distance ( $S_n$ ):

$$0.9 \, S_n \le S_r \le 1.1 \, S_n$$

#### GUARANTEED OPERATING DISTANCE (Sa)

This represents the safe sensing distance considering the manufacturing tolerances and the voltage and temperature changes. For the inductive proximity switches the guaranteed operating distance is between 0 and 81% of the rated operating distance (S<sub>n</sub>):

$$0 \le S_a \le 0.81 S_n$$

For the capacitive proximity switches the assured operating distance is between 0 and 72% of the rated operating distance  $(S_n)$ :

$$0 \le S_a \le 0.72 S_n$$

#### DIFFERENTIAL TRAVEL OR HYSTERESIS (H)

The differential travel is the difference between the switch-on point and the switch-off point with an axial motion of the target.

This is given as a percentage of the real operating distance  $(S_r)$  with a temperature of 23  $\pm$  5°C and is shown in the tables. That value is never greater than the 15% of the real operating distance  $(S_r)$ .

#### REPEAT ACCURACY (R)

The repeat accuracy (R) is the maximum variation, in percentage, of the effective operating distance ( $S_r$ ) performing several switching cycles in 8 hours with a temperature of  $23 \pm 5^{\circ}$ C and power supply changes of  $\pm 5^{\circ}$ C. The differences between measurments will never be greater than the 10% of the real operating distance:

$$R \leq 0, 1 \cdot S_r$$

#### MAX SWITCHING FREQUENCY (f)

The max switching frequency specified in the tables of the products, is measured according to fig. 2.

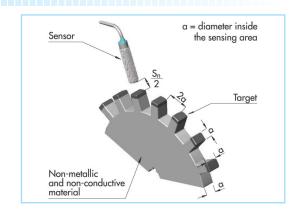


Fig. 2

#### OPERATIONAL VOLTAGE (UR)

This is the voltage range where the device will work correctly. It includes ripples and oscillations.

#### VOLTAGE DROP (Ud)

This is the voltage measured at the end of the active output of the sensor when it is passing the rated operational current (I<sub>e</sub>).

#### RATED OPERATIONAL CURRENT (Ie)

This is the maximum load current which the sensor can continuously pass at the specified temperature and operational voltage range.

#### OFF-STATE CURRENT (I<sub>r</sub>)

This is the current which flows through the 2-wire amplified sensors in the off condition. It is recommended to check that this current doesn't exceed the minimum activation current of the load.

#### MINIMUM OPERATIONAL CURRENT (Im)

This is the minimum current needed for a proper functioning of the 2-wire amplified sensors in on condition.

#### IMPULSE WITHSTAND VOLTAGE

All sensors are protected against the overvoltages coming from the supply line or from the load. The minimum value is 1KV and is tested according to EN60947-5-2 standards.

#### CHARACTERISTIC OF THE OUTPUT STAGES

#### NON AMPLIFIED IN d.c. NAMUR SERIES

The sensors of this series contain only the oscillator stage and an output filter. This allows the reduction of space and costs. Thanks to a small number of components and being used with low currents, these sensors ensure a very high reliability. The driving of a load is possible using them with a proper amplifier (AM... series. See section G) or connected to equipment with specific input stage for NAMUR devices.

ATEX sensors category 1G - 1D must be used with associated apparatus with ATEX certification.

#### **Working:**

With references to fig. 3, apply Un between 5 and 30 Volts: the I current flows through the sensor crossing the Rx resistance giving the Vo voltage. The current value will decrease in proportion to how a metal approaches its sensible surface, following the characteristic curve shown.

With Vo voltage we can control a trigger stage having then an exact switching point and giving an ON/OFF output. For the scaling of Rx look the table below:

Un (V)	<b>Rx</b> (Ω)
5	390
8,2	1000
12	1800
24	3900

It's important to consider that the NAMUR rules recommend the applications of these sensors in a supply range between 7,7 and 9 Vdc with an Rx of 1000  $\Omega$ .

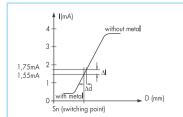
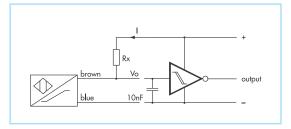


Fig. 3



#### **NAMUR WITH LED SERIES**

This series has a LED for the output condition and thanks to the integrated trigger, it has an exact switching point which permits the possibility to control PLC inputs and direct loads up to 10 mA without any interface module.



#### AMPLIFIED SERIES IN d.c. with 3 or 4-wire

The sensors in this series employ a power output stage with output protection (only K versions). They are suitable for direct driving of typical devices such as relays, PLC, contactors.

#### **OUTPUT LOGIC**

The choice for the output logic (NPN or PNP) depends on the connection type of load.

The typical output stages are shown in fig. 4. Open collector versions are available upon request.

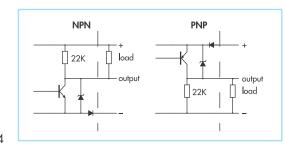


Fig. 4

#### PROTECTION AGAINST SHORT CIRCUIT

For the "K" version sensors, there is a protection against short circuits and overload in output stage. The protection is activated when the rated operational current is exceeded, blocking the current until there is a significant reduction. On d.c. sensors the sensor restarts to work as soon as the fault condition is removed. On a.c. sensors the power supply must be disconnected in order to reset the protection stage. In some cases the protection can be triggered because of high capacitive loads, like filter capacitors higher than 100 nF or lamps. In this case we recommend to use our specific proximity switches.

#### **SERIES CONNECTION: AND LOGIC**

With this connection the load is powered only when all switches are closed. The number of switches which can be connected in this way is limited by three factors:

- 1) from the residual voltage drop typical of selected switch, which is 2,2V (max for some types) at maximum load current;
- 2) from the maximum load current of switches employed, because it's important to consider that the self consumption of each sensor must be added to the final load.
- 3) from the delay time of availability. For each sensor there can be a maximum delay of 30 ms. which has to be multiplied for the number of sensors used.

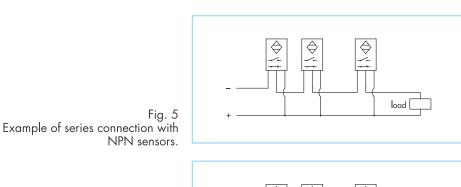
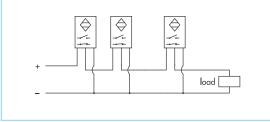


Fig. 6 Example of series connection with PNP sensors.



#### **PARALLEL CONNECTION: OR LOGIC**

With this type of connection, the load is powered whenever any of the switches are closed (or its output is conducting). In switches which are parallel connected, it must be considered that every connected sensor is loaded by other sensors internal resistor (collector resistor RC). It is possible to avoid this, using open collector types, or by introducing decoupling diodes as shown in fig 7-8.

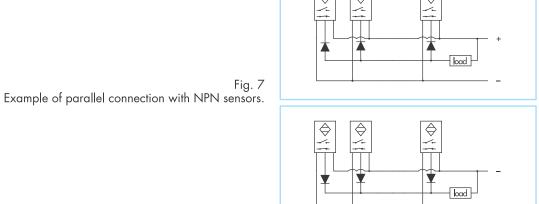


Fig. 8 Example of parallel connection with PNP sensors.

#### AMPLIFIED SERIES IN d.c. or a.c.

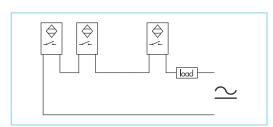
They are connected in series to the load like electro-mechanical micro-switches. It's important to verify that, after subtracting the voltage drop  $(U_d)$  from the supply voltage  $(U_B)$ , there is sufficient voltage to drive the load correctly. Another important factor in this sensor is the minimum operational current (Im), below which the sensor doesn't work properly. In open conditions, there will always be a Off-state current (Ir) which will go through the load: it is important to make sure that this current will not activate the load.

If this happens it will be necessary to connect a resistor in parallel to the load itself.

#### **SERIES CONNECTION: AND LOGIC**

If several sensors must be connected in series, it is necessary to verify that summing all the sensors voltage drops the load continues to have sufficient voltage for the correct functioning. One must also consider that in the open condition the supply voltage is divided by the number of sensors: make sure that on each sensor there is a voltage greater than the minimum value of UB.

Fig. 9 Example of series connection with 2-wire amplified sensors.



#### AMPLIFIED SERIES IN a.c. 3-wire + earth

This series of sensors (ACB, ACBF) is suitable to solve minimum load, residual current and voltage drop problems typical on 2-wire series. They have two wires for supply, one for the output and one for the earth connection.

Their connection is similar to the amplified models in d.c. (fig. 10).

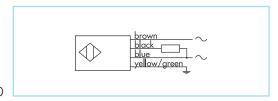


Fig. 10



#### **MOUNTING PRECAUTIONS**

Although sensors are made to resist to the most difficult conditions of use, it is recommended:

- not to wire sensors connections along with power conductors. Use of separated cable routing is recommended.
- never exceed the maximum of the fixing torque recommended for the fasteners. Bear in mind in addition that the threaded zone next to the sensing head on cylindrical products is less resistant than the rest of the body.
- make sure the product doesn't contact corrosive agents, oils, aggressive solvents, etc. Call our technical office to have further guidance on the resistance of materials to the various substances.
- avoid shocks and abrasive actions on the sensible face of the products: this area represents the most fragile zone of the device.
- the power supply circuit for sensors must be provided with suitable insulation and current limitation means.
- never use devices for the safety of machineries or people if they are not specifically recommended for that purpose. Contact our technical offices for more details.

#### CYLINDRICAL SENSORS

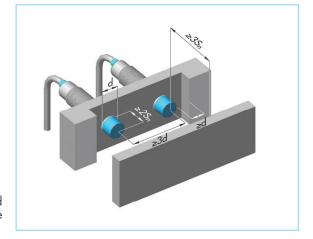
# 220

#### Totally shielded: flush mounting

Sensors are not influenced by surrounding metals.

However it's recommended to keep a distance between adjacent sensors to avoid interferences.

If this isn't possible, it's recommended the use of sensors with different frequencies for mounting alongside each other.



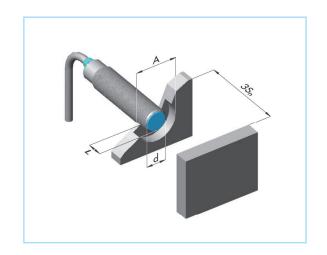
#### **Unshielded: non flush mounting**

Sensors can be influenced by surrounding metals. A distance  $\geq 3$  d between adjacent sensors is needed. For extended sensing distance versions a distance at least  $\geq 4$  d is recommended.

# Extended sensing distance and stainless steel sensing face versions: quasi flush mounting

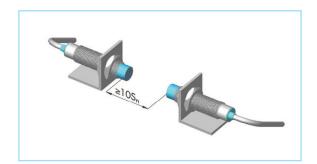
These sensors, because of their high sensitivity, are slightly sensitive to surrounding ferromagnetic metals which can reduce their sensing distance. To avoid this effect it's recommended to mount the sensor as indicated by the diagrams and charts shown.

Sensor diameter d (mm)	L min. (mm)	A min. (mm)			
6,5 - 8	1,5	12			
12	2,4	18			
18	3,6	28			
30	8	45			



#### **Opposed mounting of two sensors**

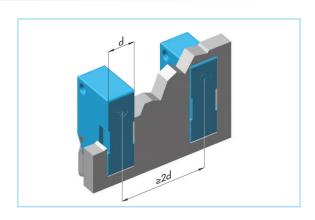
A minimum distance of 10  $\rm S_{\rm n}$  ensures non interference between electromagnetic fields.

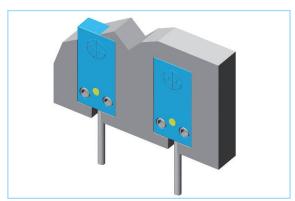


### RECTANGULAR SENSORS

#### **Totally shielded: flush mounting**

Sensors are not influenced by surrounding metals. However it's recommended to keep a distance between adjacent sensors to avoid interferences. If this isn't possible, it's recommended to use sensors with different frequencies when mounting side by side.

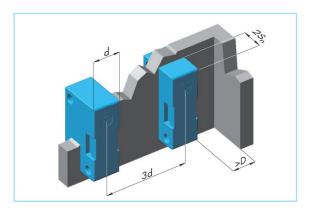


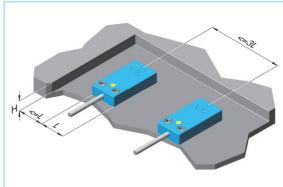


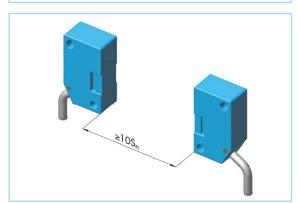


#### **Unshielded: non flush mounting**

Sensors can be influenced by surrounding metals. It's necessary to have more space between adjacent sensors.



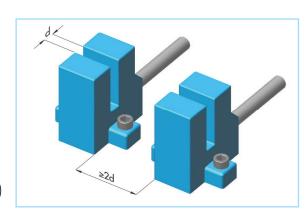




#### **Opposed mounting of two sensors**

A minimum distance of 10  $\rm S_{\rm n}$  ensures non interference between electromagnetic fields.

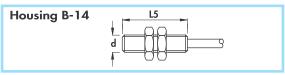
#### SLOT SENSORS

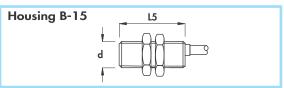


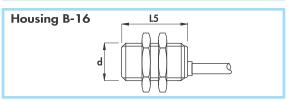
It's recommended to keep a distance of twice the slot width (d) between adjacent sensors.

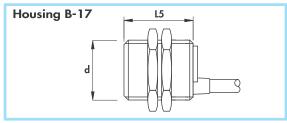
#### CYLINDRICAL INDUCTIVE SENSORS IN PLASTIC HOUSING

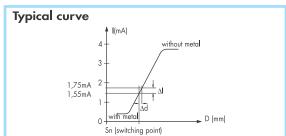
- NAMUR SERIES
- Non-amplified in d.c. 2-wire
- Cable output











Diamet	ter	M8 x 1	M12 x 1	M18 x 1	M30 x 1,5
Nut	Size	SW13	SW17	SW24	SW36
1401	Thickness mm	4	4	4	5
Max tiç torque	ghtening Nm	1	1	5	20

#### **Materials:**

- 2 m PVC CEI 20 22 II; 90°C; 300 V; O.R. Cable: Housing: plastic
- Sensing face:

Technical data:

Working voltage: Supply voltage according to NAMUR:

Max ripple:

plastic

Consumption at 8,2 V con Rx =  $1000 \Omega$ with metal:

without metal:

Temperature range:

Max thermal drift of sensing distance S<sub>r</sub>:

Repeat accuracy (R):

Degree of protection: Cable conductor cross section:

10%  $\leq 1 \text{ mA}$ 

≥3 mA - 25° ÷ + 70°C ± 10% 2% IP67

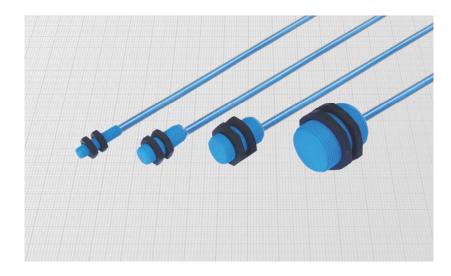
5 ÷ 30 Vdc

7,7 ÷ 9 Vdc

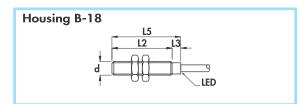
 $0.35 \text{ mm}^2$  on 8 and 12 mm $0.75 \text{ mm}^2 \text{ on } 18 \text{ and } 30 \text{ mm}$ 

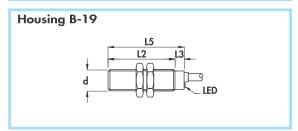
- According to EN60947.5-6

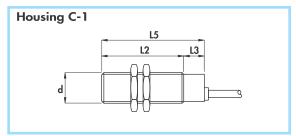
D D	Flush mounting Non flush mounting	L1	L2	L3	L4	L5	Cable diameter	Body diamefer ( d )	Max switching frequency (f)	Nominal sensing distance (S <sub>n</sub> ) ± 10%	ORDERING REFERENCES
Housing	ush mo n flush n						O <u>.</u> <u>e</u>	dia D	Max s freque	Nomin distand	boown blue +
	E S	mm	mm	mm	mm	mm	mm	mm	KHz	mm	Julie –
B-14 B-14		-	-	-	-	30 30	4 4	M8 x 1 M8 x 1	5 3	1,5 2,5	DC8P/4600 DC8P/5600
B-15 B-15		- -	- -	- -	- -	30 30	4 4	M12 x 1 M12 x 1	5 1	2 4	DC12P/4600 DC12P/5600
B-16 B-16		- -	- -	- -	- -	30 30	5 5	M18 x 1 M18 x 1	1 0,5	5 8	DC18P/4600 DC18P/5600
B-17 B-17	•	-	- -	-	-	35 35	5 5	M30 x 1,5 M30 x 1,5	0,3 0,2	10 15	DC30P/4600 DC30P/5600



- Diameters 8 12 18 mm •
- Amplified in d.c. 3 and 4-wire
  - Cable output •





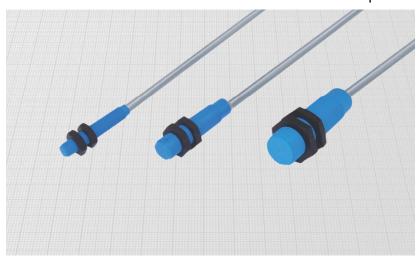


Diamet	er	M8 x 1	M12 x 1	M18 x 1		
Nut	Size	SW13	SW17	SW24		
INUI	Thickness mm	4	4	4		
Max tig	htening Nm	1	1	5		

#### Materials:

2 m PVC CEI 20 - 22 II; 90°C; 300 V; O.R. Cable:

Housing: plastic Sensing face: plastic



#### Technical data:

Supply voltage (U<sub>B</sub>):

Max ripple: No-load supply current (I<sub>o</sub>):

Voltage drop  $(\dot{U}_d)$ :

Temperature range:

Max thermal drift of sensing distance S<sub>r</sub>:

Repeat accuracy (R):

Switching hysteresis (H):

Degree of protection:

Switch status indicator:

Cable conductor cross section:

see ordering references

 $\leq 10 \text{ mA}$ 

on 8 and 12 mm  $\leq$  1,5 V

on  $18 \text{ mm} \le 2.2 \text{ V}$ 

- 25° ÷ + 70°C

2% 10%

**IP67** 

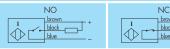
yellow LED 0,22 mm<sup>2</sup> on 8 mm 0,35 mm<sup>2</sup> on 12 mm 0,50 mm<sup>2</sup> on 18 mm

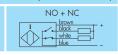
Protected against short-circuit and overload Protected against any wrong connection

Suppression of initial false impulse

D	p.	Flush mounting Ion flush mounting	L2	L3	L5	Cable diameter	Body diamefer ( d )	Supply voltage (UB)	Max switching frequency (f)	Rated operational current ( l <sub>e</sub> )	Nominal sensing distance $(S_n) \pm 10\%$				
Housing		om r ush r				0.8	B is	S	Aax s	red o	lomir		PNP (positive switching)		
		Plus Non fi							<b>~</b> Ψ	Ra	Zisib	NO NC brown + I black +		NO + NC	
			mm	mm	mm	mm	mm	(min - max)	KHz	mA	mm	blue	blue	white	
B -1 B -1		•	40 40	7 7	47 47	3,5 3,5	M8 x 1 M8 x 1	7÷30 7÷30	4 3	200 200	1,5 2,5	DCA8P/4609KS DCA8P/5609KS	DCA8P/4619KS DCA8P/5619KS	DCA8P/4629KS DCA8P/5629KS	
B -1 B -1		•	42 42	8 8	50 50	4 4	M12 x 1 M12 x 1	5÷40 5÷40	2 1,5	200 200	2 4	DCA12P/4609KS DCA12P/5609KS	DCA12P/4619KS DCA12P/5619KS	DCA12P/4629KS DCA12P/5629KS	
C -		•	50 50	10 10	60 60	5 5	M18 x 1 M18 x 1	5÷60 5÷60	1 1	400 400	5 8	DCA18P/4609KS DCA18P/5609KS	DCA18P/4619KS DCA18P/5619KS	DCA18P/4629KS DCA18P/5629KS	

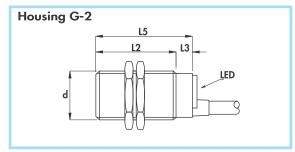
NPN (negative switching)
Use the above mentioned part number changing the last number 9 with 8 (ie. DCA8P/4608KS)

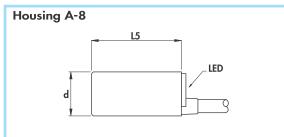




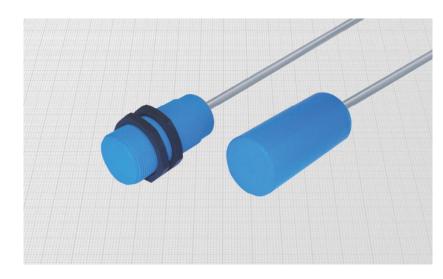
#### CYLINDRICAL INDUCTIVE SENSORS IN PLASTIC HOUSING

- Amplified in d.c. 3 or 4-wire
- Diameters 30 34 mm
- Cable output





Diam	eter	M30 x 1,5							
Nut	Size	SW36							
1401	Thickness mm	5							
Max torqu	tightening e Nm	20							



#### **Materials:**

Cable: 2 m PVC CEI 20 - 22 II; 90°C; 300 V; O.R. Housing; plastic plastic Sensing face:

Technical data:

Supply voltage (U<sub>B</sub>): Max ripple: No-load supply current (I<sub>o</sub>): Voltage drop (U<sub>d</sub>): Temperature range:

Max thermal drift of sensing distance S<sub>r</sub>:

Repeat accuracy (R):

Switching hysteresis (H): Degree of protection: Switch status indicator:

Cable conductor cross section

Protected against short-circuit and overload

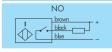
Protected against any wrong connection Suppression of initial false impulse

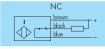
Electromagnetic compatibility (EMC) according to EN60947-5-2

Shock and vibration resistance according to EN60068-2-27 EN60068-2-6

ng	n mounting ush mounting	L2	L3	L5	Cable diameter	Body diameter ( d )	Max switching frequency (f)	Rated operational current (1 <sub>e</sub> )	al sensing (S <sub>n</sub> ) ± 10%			
Housing	mo Ish r				O <u>.</u> 8	B.ö	nbe.	o pa conii	Nominal s distance (S <sub>n</sub>		PNP (positive switching)	
T	Flush Non flush						≥⊭	Rat	Aisib	NO brown +	NC brown +	NO + NC  black +
		mm	mm	mm	mm	mm	KHz	mA	mm	blue	blue	white blue
G-2 G-2	•	50 50	10 10	60 60	6 6	M30 x 1,5 M30 x 1,5	0,8 0,4	400 400	10 15	DCA30P/4609KS DCA30P/5609KS	DCA30P/4619KS DCA30P/5619KS	DCA30P/4629KS DCA30P/5629KS
A - 8	•	-	-	70	6	34	0,2	400	20	DCA34P/5609LKS	DCA34P/5619LKS	DCA34P/5629LKS

NPN (negative switching) Use the above mentioned part number changing the last number 9 with 8 (ie. DCA30P/4608KS)







7 ÷ 60 Vdc 10%

 $\leq 10 \text{ mA}$ ≤ 2,2 V - 25° ÷ + 70°C

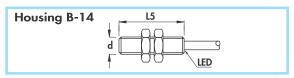
 $\pm 10\%$ 2% 10%

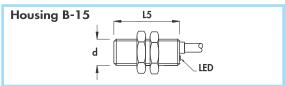
IP67

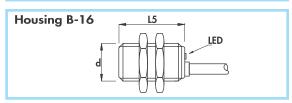
yellow LED

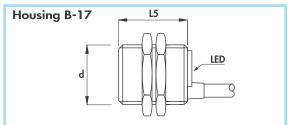
'0,50 mm<sup>2</sup>

- **SHORT SERIES** •
- Amplified in d.c. 3-wire
  - Cable output •









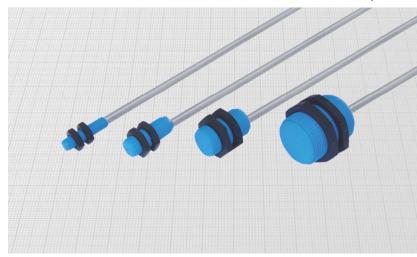
Diamet	er	M8 x 1	M12 x 1	M18 x 1	M30 x 1,5
Nut	Size	SW13	SW17	SW24	SW36
11101	Thickness mm	4	4	4	5
Max tiq	ghtening Nm	1	1	5	20

#### Materials:

2 m PVC CEI 20 - 22 II; 90°C; 300 V; O.R. Cable: plastic

Housing: plastic

Sensing face:



#### Technical data:

Supply voltage (U<sub>B</sub>): Max ripple:

No-load supply current (I<sub>o</sub>): Voltage drop (U<sub>d</sub>):

- Temperature range: Max thermal drift of sensing distance S<sub>r</sub>:
- Repeat accuracy (R):
- Switching hysteresis (H): Degree of protection:
- Switch status indicator:
- Cable conductor cross section:

see ordering references

10%  $\leq 10 \text{ mA}$ 

≤ 1,5 V  $-25^{\circ} \div + 70^{\circ}C$ 

± 10%

2% 10%

**IP67** 

yellow LED 0,22  $\text{mm}^2$  on 8 mm

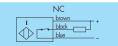
 $0.35 \, \text{mm}^2 \, \text{on} \, 12 \, \text{mm}$  $0.50 \text{ mm}^2$  on 18 and 30 mm

- Protected against short-circuit and overload
- Protected against any wrong connection Suppression of initial false impulse

Da	unting	L1	L2	L3	L4	L5	Cable diameter	Body diameter ( d )	Supply voltage (UB)	Max switching frequency (f)	Rated operational current (1 <sub>e</sub> )	Nominal sensing distance $(S_n) \pm 10\%$		ERING ENCES
Housing	Flush mounting Non flush mounting						<u>0.9</u>	a gip	NS OF	Max s		Nomin	NO brown	ve switching)  NC  brown  t
		mm	mm	mm	mm	mm	mm	mm	V (min - max)	KHz	mA	mm	blue	black
B -14 B -14	•	- -	- -	-	-	30 30	3,5 3,5	M8 x 1 M8 x 1	7 ÷ 30 7 ÷ 30	4 3	200 200	1,5 2,5	DSA8P/4609KS DSA8P/5609KS	DSA8P/4619KS DSA8P/5619KS
B -15 B -15	•	- -	- -	- -	- -	30 30	4 4	M12 x 1 M12 x 1	7 ÷ 40 7 ÷ 40	2 1,5	200 200	2 4	DSA12P/4609KS DSA12P/5609KS	DSA12P/4619KS DSA12P/5619KS
B -16 B -16	•	- -	- -	- -	- -	30 30	5 5	M18 x 1 M18 x 1	5 ÷ 40 5 ÷ 40	0,8 0,6	200 200	5 8	DSA18P/4609KS DSA18P/5609KS	DSA18P/4619KS DSA18P/5619KS
B -1 <i>7</i> B -1 <i>7</i>	•	-	- -	- -	- -	35 35	6 6	M30 x 1,5 M30 x 1,5	7 ÷ 40 7 ÷ 40	0,8 0,4	200 200	10 15	DSA30P/4609KS DSA30P/5609KS	DSA30P/4619KS DSA30P/5619KS

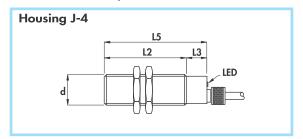
NPN (negative switching) Use the above mentioned part number changing the last number 9 with 8 (ie. DSA8P/4608KS)





#### CYLINDRICAL INDUCTIVE SENSORS IN PLASTIC HOUSING

- Degree of protection IP68
- Amplified in d.c. 3 and 4-wire
- Cable output

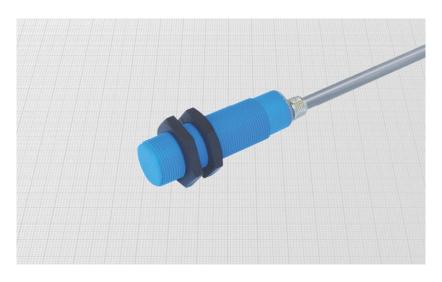


Diameter		M18 x 1			
Nut	Size	SW24			
	Thickness mm	4			
Max tightening torque Nm		5			



2 m PVC CEI 20 - 22 II; 90°C; 300 V; O.R. Cable: Housing: plastic

nickel plated brass Gland: Sensing face: plastic



#### **General Features:**

This new series solves definitively the problem of the ingress of liquids to the inner parts of the sensors. Thanks to the inner hermetic sealing they can be subjected to non-stop jets of liquids under pressure even in presence of temperature changes. They find applications in automatic washing machinery, in machines subject to water jets and in continuous immersion applications.

#### Technical data:

Supply voltage (U<sub>B</sub>): Max ripple:

No-load supply current (I<sub>o</sub>): Voltage drop (U<sub>d</sub>):

Temperature range:

Max thermal drift of sensing distance S<sub>r</sub>:

Repeat accuracy (R):

Switching hysteresis (H): Degree of protection:

Switch status indicator:

Cable conductor cross section:

Protected against short-circuit and overload

Protected against any wrong connection

Suppression of initial false impulse

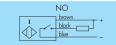
Electromagnetic compatibility (EMC) according to EN60947-5-2

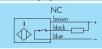
Shock and vibration resistance according to EN60068-2-27 EN60068-2-6

Rated operational current (1<sub>e</sub>) Nominal sensing distance  $(S_n) \pm 10\%$ **ORDERING** Max switching frequency (f) **REFERENCES** L2 L3 L5 PNP (positive switching) NO NO + NC black black mm mm mm mm mm KHz mΑ mm 5 DCA18P/4609KSJ DCA18P/4619KSJ DCA18P/4629KSJ 1-4 50 10 60 5 M18 x 1 1 400 50 10 60 5 M18 x 1 1 400 8 **DCA18P/5609KSJ** DCA18P/5619KSJ DCA18P/5629KSJ J-4

NPN (negative switching)

Use the above mentioned part number changing the last number 9 with 8 (ie. DCA18P/4608KSJ)







5 ÷ 60 Vdc 10%

 $-25^{\circ} \div + 70^{\circ}C$ 

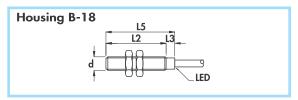
 $\leq 10 \text{ mA}$ 2,2 V

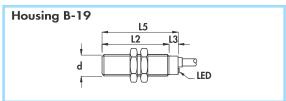
> ± 10% 2% 10%

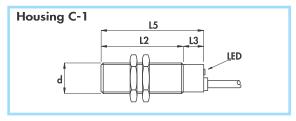
**IP68** yellow LED

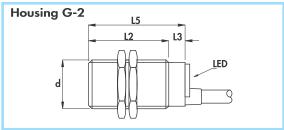
'0,50 mm<sup>2</sup>

- Diameters 8 30 mm •
- Amplified in a.c. 2-wire
  - Cable output •









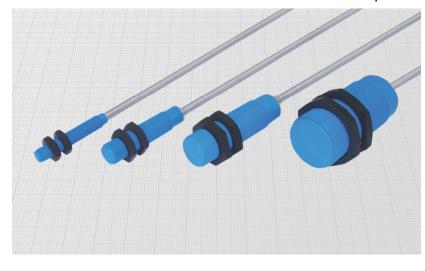
Diamete	er	M8 x 1	M12 x 1	M18 x 1	M30 x 1,5
Nut	Size	SW13	SW17	SW24	SW36
	Thickness mm	4	4	4	5
Max tightening torque Nm		1	1	5	20

#### **Materials:**

Cable: Housing:

Sensing face:

2 m PVC CEI 20 - 22 II; 90°C; 300 V; O.R. plastic plastic



#### Technical data:

Supply voltage (U<sub>B</sub>): Electrical system frequency:

Off-state current ( $I_r$ ):

Minimum operational current  $(I_m)$ : Voltage drop  $(U_d)$ :

Temperature range:
Max thermal drift of sensing distance S<sub>r</sub>:

Repeat accuracy (R):

Switching hysteresis (H):

Degree of protection:

Switch status indicator:

Cable conductor cross section:

20 ÷ 240 Vac 40 ÷ 60 Hz  $\leq$ 1,5 mA at 110 Vac

5 mA

≤5 V -25° ÷ + 70°C

2% 10%

± 10%

**I**P67

yellow LED 0,35 mm<sup>2</sup> on 8 and 12 mm 0,50 mm<sup>2</sup> on 18 mm  $0.75 \text{ mm}^2 \text{ on } 30 \text{ mm}$ 

Suppression of initial false impulse

Suppression of initial talse impulse
Class 2 equipment according to EN61140
Shock and vibration according to EN60068-2-27 EN60068-2-6
Electromagnetic compatibility (EMC) according to EN60947-5-2

ng unting ounting	unting nounting	LI	L2	L3 L4	L4	L5	Cable diameter	Body diameter ( d )	Max switching frequency (f) Rated operational current (L)	perational ent (1 <sub>e</sub> )	Nominal sensing distance (S <sub>n</sub> ) ± 10%	ORDERING REFERENCES	
Housi	Housing Flush mounting Non flush mounting									Rated o		NO block	NC block ~~
		mm	mm	mm	mm	mm	mm	mm	Hz	mA	mm		
B -18 B -18	•	- -	40 40	7 7	- -	47 47	4 4	M8 x 1 M8 x 1	25 25	100 100	1,5 2,5	AC8P/4609S AC8P/5609S	AC8P/4619S AC8P/5619S
B-19 B-19	•	- -	42 42	8 8	- -	50 50	4 4	M12 x 1 M12 x 1	25 25	500 500	2 4	AC12P/4609S AC12P/5609S	AC12P/4619S AC12P/5619S
C -1 C -1	•	- -	50 50	10 10	-	60 60	5 5	M18 x 1 M18 x 1	25 25	500 500	5 8	AC18P/4609S AC18P/5609S	AC18P/4619S AC18P/5619S
G-2 G-2	•	- -	50 50	10 10	- -	60 60	6 6	M30 x 1,5 M30 x 1,5	25 25	500 500	10 15	AC30P/4609S AC30P/5609S	AC30P/4619S AC30P/5619S